

- Office hours Mon 11-12
- HW posted; Submit in groups of 3-4.
- Script + volunteers \rightarrow count as 1 HW.

Clarifications (Thanks to all who pointed out)

①

Abbildung
" Map

Karte
" Chart

Key ideas for today

* Tangent space already tells you about ~~old~~ world
 alternative - - - - map

Next 2 lectures

* ways of building manifolds from other manifolds

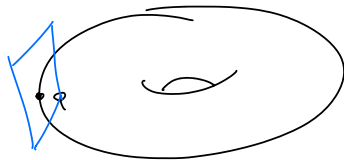
For today, world = subset of \mathbb{R}^n

Monday

$S \subseteq \mathbb{R}^n$ is locally a graph $\mathbb{R}^d \rightarrow \mathbb{R}^{n-d}$ \implies $S \subseteq \mathbb{R}^n$ is a d -manifold

Today

Def



We need a way to choose the d coords

all we have are $\psi: U \rightarrow S$ and $\psi^{-1}: V \rightarrow U$

Target space

Prop $d\psi_{\tilde{z}}: \mathbb{R}^d \rightarrow \mathbb{R}^n$ is injective $\forall \tilde{z}$

Γ $d\psi^{-1} \circ d\psi: \mathbb{R}^d \rightarrow \mathbb{R}^d = \mathbb{1} \downarrow$ Chain rule!

Prop $\text{Image}(d\psi_{\tilde{z}})$ does not depend on the chart

Γ $\begin{array}{ccc} & S & \\ \psi \nearrow & & \nwarrow \tilde{\psi} \\ U & \xleftarrow{\psi^{-1} \circ \tilde{\psi}} & \tilde{U} \end{array}$ $d(\tilde{\psi}) = d\psi \circ d(\psi^{-1} \circ \tilde{\psi}) \downarrow$

all invertible

Defn $T_p S := \text{Image of } d\psi_{\psi^{-1}(p)}$

(notes ψ^{-1} does not determine $T_p S$)

Prop $d\psi: \mathbb{R}^d \rightarrow T_p S$ is an isomorphism

Cor If S is locally a graph over \mathbb{R}^d , then $\pi: \mathbb{R}^n \rightarrow \mathbb{R}^d$

$d\pi: T_p S \rightarrow \mathbb{R}^d$ is an isomorphism.

Γ π is the inverse of a chart \downarrow

For the course, need:

Thm (Inverse Function theorem) $f: U \rightarrow \mathbb{R}^d$ smooth
 If $df_p: \mathbb{R}^d \rightarrow \mathbb{R}^d$ is invertible, then f is locally (smoothly) invertible at p . (a local diffeomorphism)

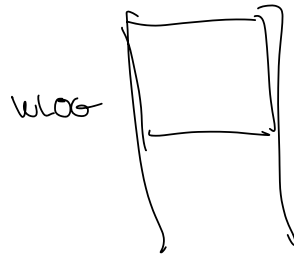
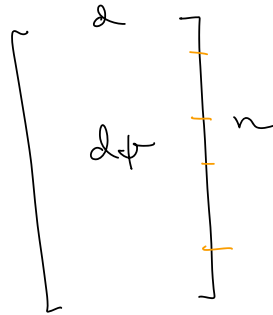
Warning: local maps may be unphysical domain; if you like, everything today is about groups of maps.

End of graph of graph then:

Let $q \in S$, $\psi: U \rightarrow S$ be a chart at q ;

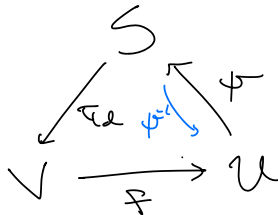
$d\psi$ injective
 \Rightarrow some $d \times d$ minor is invertible

Choose this π



then $d(\pi \circ \psi)$ is an isomorphism

IFT \Rightarrow It has a local inverse $F \circ (\pi \circ \psi) \circ F = 1_V$
 $F \circ (\pi \circ \psi) = 1_U$



Claim $(\psi \circ F)$ presents S locally as a graph.

$\pi \circ (\psi \circ F) = id_V \Rightarrow \psi \circ F(x_1, \dots, x_d) = (x_1, \dots, x_d, (\psi \circ F)(x_1, \dots, x_d) \dots (\psi \circ F)(x_1, \dots, x_d))$

need
 $\psi \circ F \circ \pi|_S = id_S$ locally

\leftarrow conjugate by F

- Jan/codons
- word definition

Ways of getting new manifolds from old

- products (HW)

$$S \subseteq \mathbb{R}^n \longrightarrow S \times \hat{S} \subseteq \mathbb{R}^{n+m}$$

$$\hat{S} \subseteq \mathbb{R}^m$$

- graphs \longrightarrow level sets
 \downarrow generalises to
 parametrizations (Gauss)

Images / embeddings / parametrizations

Def: $\psi: U \xrightarrow{\text{std}} \mathbb{R}^n$ is an embedding if $\psi: U \rightarrow \psi(U)$ is a diffeomorphism.

Def: Immersion

(so emb \Rightarrow imm, but not conversely)



But a graph is an embedding, so:

Thm If $\psi: U \xrightarrow{\text{std}} \mathbb{R}^n$ is an immersion, then it is locally (in U) an embedding.

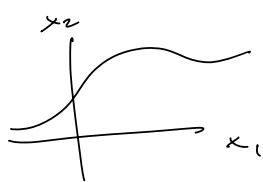
(note similarity - differences to above)

As above, choose $\mathbb{R}^d \subseteq \mathbb{R}^n$ s.t.
$$\begin{array}{ccc} & \mathbb{R}^d & \\ \uparrow & & \downarrow \text{std} \\ U \subseteq \mathbb{R}^d & \xrightarrow{\psi} & \mathbb{R}^n \end{array}$$
 locally invertible

(on the whole domain)

then $\psi \circ \mathbb{F}$ is a graph, so it's an embedding \downarrow
 \mathbb{R}^d

Straightening a graph example:



$$x_2 = f(x_1)$$

$$\tilde{x}_1 = x_1$$

$$\tilde{x}_2 = x_1 - f(x_1)$$

$$\Rightarrow \begin{bmatrix} \frac{\partial \tilde{x}_1}{\partial x_i} \\ \frac{\partial \tilde{x}_2}{\partial x_i} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -f' & 1 \end{bmatrix}$$

invertible (eg determinant $\neq 0$)

HW: (canonical form of an immersion)

every immersion, in some coords, is the inclusion $\iota: \mathbb{R}^d \rightarrow \mathbb{R}^n$.

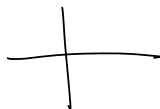
Submersion / Level sets

$$U \subseteq \mathbb{R}^n \text{ open, } f: U \rightarrow \mathbb{R}^{n-d}$$

when is $f^{-1}(0)$ a d -submanifold of U ?

convex

$$f(x,y) = xy$$



$$f(x,y) = x^2 + y^2$$

(level set — condition decreases dim by 1)

Thus for $p \in f^{-1}(0)$, if Df_p is surjective, then $f^{-1}(0)$ is a manifold near p .

$$T \quad n-d \quad \begin{bmatrix} \dots & \dots & \dots & \dots \\ & & Df_p & \\ & & & \dots \\ & & & \dots \end{bmatrix}$$

$$\text{WLOG} \quad \begin{bmatrix} \boxed{1 \dots 1} & 0 \\ \dots & \dots \\ \dots & \dots \\ \dots & \boxed{\text{invertible}} \end{bmatrix}$$

$$\text{get map } \mathbb{R}^n \rightarrow \mathbb{R}^d \times \mathbb{R}^{n-d}$$

$$x_1 \dots x_n \mapsto (x_1 \dots x_d) \times (x_{d+1} \dots x_n)$$

IFT \rightarrow local inverse $G(x_1 - x_2, y_1 - y_2)$
 then $G(x_1 - x_2, 0 - 0)$ is a chart
 w/ inverse (x_1, \dots, x_n)

Another way of saying this; IFT $\Rightarrow (x_1 - x_2, y_1 - y_2)$
 are local coords. They clearly straighten fibers.

Thm (canonical form of a submersion) \exists
 coords st. the submersion is then:

Note If π is a submersion, $T_p \pi^{-1}(0) = \ker(d\pi_p)$

Thm: If $F: U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$, $S \subseteq \mathbb{R}^m$ submanifold,
 and $\ker(dF_p) \oplus T_p S = \mathbb{R}^m$, then $F^{-1}(S)$ is a
 $(n-r)$ -submanifold.

- Γ
- WLOG, near p , $S = \mathbb{R}^{m-r} \subseteq \mathbb{R}^m$ (Fund thm of calc)
 - $S \xrightarrow{m-r} \mathbb{R}^r$ is a submersion at p \downarrow

Defn (Transversality)

- If $F: U \rightarrow \mathbb{R}^m$, $S \subseteq \mathbb{R}^m$
 $F \pitchfork S$ if $\ker(dF_p) \oplus T_p S = \mathbb{R}^m \quad \forall p \in F^{-1}(S)$
- If $S, \hat{S} \subseteq \mathbb{R}^m$, $S \pitchfork \hat{S}$ if $T_p \hat{S} \oplus T_p S = \mathbb{R}^m \quad \forall p \in S \cap \hat{S}$
- If $F, G: U \rightarrow \mathbb{R}^m$, $F \pitchfork G$ if $\forall p \in U$ s.t. $F(p) = G(p)$,
 $dF_p - dG_p: T_p U \rightarrow \mathbb{R}^m$

Application

- $S \cap \hat{S} \Rightarrow \mathcal{F}(S)$ subfield
- $S \cap \hat{S} \Rightarrow S \cap \hat{S}$ subfield (apply to $F = U: \hat{S} \rightarrow \mathbb{R}^m$)
- $F \cap g \Rightarrow \{F=g\}$ subfield (dim $n-m$)

$$U \stackrel{\mathbb{R}^n}{\xrightarrow{\begin{matrix} F \\ g \end{matrix}}} \mathbb{R}^m$$

↑

$(F, g) \cap \Delta$ where

$(F, g): U \rightarrow \mathbb{R}^{2m}$, $\Delta \subseteq \mathbb{R}^{2m}$ is the diagonal ↓

Remark Everything makes sense with \mathbb{R}^n replaced by an n -dim manifold, e.g.

Then (IFT for submanifolds)

IF S, \hat{S} subflds, $dF_p: T_p S \rightarrow T_{F(p)} \hat{S}$ is an isomorphism, then F is a local diffeomorphism.

$$\begin{array}{ccc} S & \xrightarrow{F} & \hat{S} \\ \uparrow \psi & & \uparrow \hat{\psi} \\ U & \xrightarrow{\quad} & \hat{U} \end{array} \quad \downarrow$$

IFT

and

if $S \xrightarrow{f} X$, say f transverse to g ($f \pitchfork g$)

if $\forall p \in S$ w/ $f(p) = g(p)$, $\text{image}(df_p - dg_p) = T_p X$

Then if $f \pitchfork g$, then $\{f=g\}$ is a submanifold of S

$T_p \{f=g\} \subseteq T_p X = \mathbb{R}^n$, can apply submersion theorem to $f-g$.

• In general, choose a local diffeo $X \simeq \mathbb{R}^n$ \downarrow

Note if $S, \hat{S} \subseteq X$, then $S \pitchfork \hat{S} \Leftrightarrow L_S \pitchfork L_{\hat{S}}$